



MACHINEX







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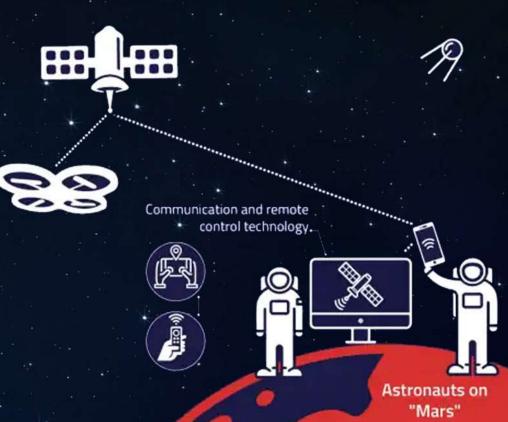
OLEKSANDR BOIKO RESEARCH AND DEVELOPMENT

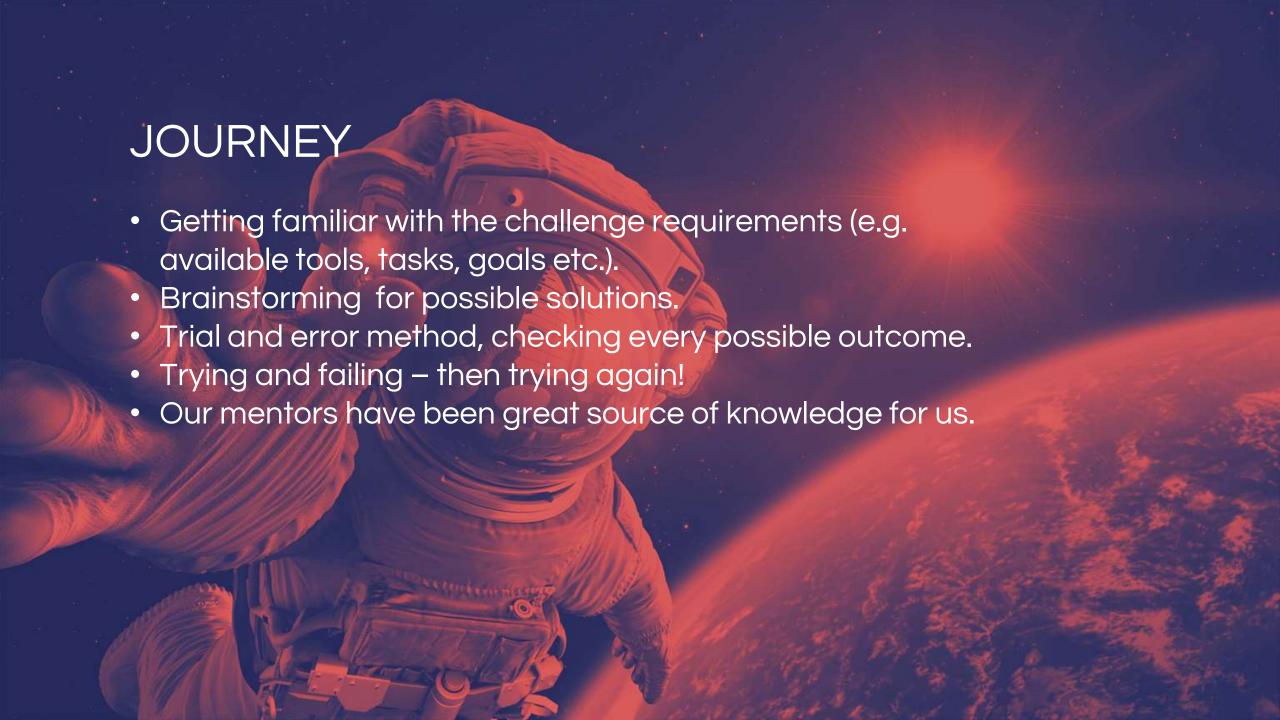
Transportation Challenge

Goal: Create a robotic device that can be remotely guided to deliver a payload to a specific location in the environment.

Aim: Transport a payload from an unknown location to a specific coordinates by utilising a remotely controlled transportation device.







CONCEPT 1: DISCOVERY



DEVICE SETUP

1 CAMERA 1 LASER 1 SELFIE STICK

UNCERTAINTIES

STABILITY OF THE SYSTEM

STICK HEIGHT

MEASUREMENT ACCURACY

CONCEPT 2: DISCOVERY 3D



DEVICE SETUP

ZACTION CAMERAS 1 HOLDER

UNCERTAINTIES

IMPLEMENTATION COMPLEXITY

BIG DATA

HEAVY REAL-TIME PROCESSING

CONCEPT 3: DISCOVERY X



DEVICE SETUP

1 ACTION CAMERA 1 CAMERA 2LASERS 1 SELFIE STICK

UNCERTAINTIES

STABILITY OF THE SYSTEM

MAPPING COMPLEXITY

SETUP IMPROVEMENTS AND FUTURE POSSIBILITIES

- Stability of system is increased by reducing number of camerasand lasers and by proper weight distribution
- The device setup overall is simplified after testing
- Mapping system is adjusted due to results of testing
- Driver skills improved
- Rear View Camera

FINAL CONCEPT: DISCOVERY F



- One car
- One selfie stick
- One phone
- One laser
- Rear View Camera

WHAT IS NEXT?



Create a business model and start collaboration with Parcel delivery services and propose using machines as postman

THANKYOUFORATTENTION

